

Centralized systemic risk control in the interbank system: weak formulation and Gamma-convergence

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Joint work with T. Li and X. Yu

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Talk Outline

- 1 Background
- 2 Model Setup and Problem Formulation
- 3 Limit of Optimization Problem
- 4 Gamma-Convergence

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Mean Field Model I

- [Fouque and Sun \(2013\)](#): Systemic risk illustrated. *Handbook on Systemic Risk*, J.P. Fouque and J.A. Langsam Eds, Cambridge University Press.

$$dX_t^i = \frac{a}{N} \sum_{j=1}^N (X_t^j - X_t^i) dt + \sigma dW_t^i, \quad i = 1, \dots, N.$$

- [Bo and Capponi \(2015\)](#): Systemic risk in interbanking systems. *SIAM J. Finan. Math.* 6, 386-424.
- [Biagini et al. \(2019\)](#): Financial asset bubbles in banking networks. *SIAM J. Finan. Math.* 10(2), 430-465.
- [Capponi et al. \(2020\)](#): A dynamic system model of interbank lending-systemic risk and liquidity provisioning. *Math. Oper. Res.* 45(3), 1127-1152.

Controlled Mean Field Model I

- [Carmona et al. \(2015\)](#): Mean field games and systemic risk. *Commun. Math. Sci.* 13(4), 911-933.

$$dX_t^i = \frac{a}{N} \sum_{j=1}^N (X_t^j - X_t^i) dt + \theta_t^i dt + \sigma dW_t^i + \sigma_0 dW_t^0, \quad i = 1, \dots, N.$$

- Aim to minimize

$$J^i(\theta^1, \dots, \theta^N) = \mathbb{E} \left[\int_0^T f_i(X_t, \theta_t^i) dt + g_i(X_T^i) \right],$$

where

$$f_i(x, \theta^i) = (\theta^i)^2 + \frac{q}{2} (\bar{x} - x^i)^2, \quad g_i(x) = \frac{c}{2} (\bar{x} - x^i)^2$$

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Financial Model I

- The log-monetary reserve of bank i satisfies

$$dX_t^{\theta,i} = \frac{a_i}{N} \sum_{j=1}^N (X_t^{\theta,j} - X_t^{\theta,i}) dt + u_i \theta_t dt + \sigma_i dW_t^i + \sigma_0 dW_t^0, \quad t \in (0, T].$$

- 1 **Type vector:** $\xi^i := (a_i, u_i, \sigma_i)^\top \in \mathcal{O} := \mathbb{R}_+^3$.
- 2 **Control rate** implemented by the central bank: θ_t .
- 3 **Target log-monetary reserve level** determined by the central bank: Y^i .

Financial Model II

- Objective functional

$$J_N(\theta) = \mathbb{E} \left[L_N(\mathbf{X}_T^{\theta,N}, \mathbf{Y}^N) + \int_0^T R_N(\mathbf{X}_t^{\theta,N}, \mathbf{Y}^N; \theta_t) dt \right],$$

where $\mathbf{X}_t^{\theta,N} := (X_t^{\theta,1}, \dots, X_t^{\theta,N})^\top$, $\mathbf{Y}^N := (Y^1, \dots, Y^N)^\top$.

- Loss function

$$L_N(\mathbf{x}, \mathbf{y}) := \frac{\alpha}{N} \sum_{i=1}^N L(x_i, y_i), \quad R_N(\mathbf{x}, \mathbf{y}; \theta) := \frac{\beta}{N} \sum_{i=1}^N L(x_i, y_i) + \lambda \theta^2,$$

where $L(x_i, y_i) := |x_i - y_i|^2$.

Financial Model III

- Control problem under **strong formulation**:

$$\mathbb{U}^{\mathbb{P},\mathbb{F}} := \{\theta \in \mathbb{H}^2; \theta_t(\omega) \in \Theta \text{ a.s. on } [0, T] \times \Omega\},$$

where \mathbb{H}^2 is the space of all \mathbb{F} -adapted and real-valued processes $\theta = (\theta_t)_{t \in [0, T]}$ satisfying $\mathbb{E}[\int_0^T |\theta_t|^2 dt] < \infty$.

- Assumption (\mathbf{A}_{s1})**: There exists a global constant K such that $|\xi_i| \leq K$ for all $i \geq 1$. The sequence of initial log-monetary reserves $\{X_0^i\}_{i \in \mathbb{N}}$ satisfies $\sup_{i \in \mathbb{N}} \mathbb{E}[|X_0^i|^{2+\varrho}] < \infty$ for some $\varrho > 0$.
- Assumption (\mathbf{A}_Θ)**: The policy space of $\Theta \subset \mathbb{R}$ is a (nonempty) compact and convex set.

Optimal Control with Finite Banks I

- Rewrite the system in a compact form:

$$d\mathbf{X}_t^\theta = \mathbf{b}(\mathbf{X}_t^\theta, \theta_t)dt + \Sigma d\mathbf{W}_t^0, \quad t \in [0, T],$$

- The drift term is defined by:

$$\begin{aligned} \mathbf{b}(\mathbf{X}_t^\theta, \theta_t) &:= \frac{1}{N} \begin{bmatrix} (1-N)a_1 & a_1 & \cdots & a_1 \\ a_2 & (1-N)a_2 & \cdots & a_2 \\ \vdots & \vdots & \ddots & \vdots \\ a_N & a_N & \cdots & (1-N)a_N \end{bmatrix} \begin{bmatrix} X_t^{\theta,1} \\ X_t^{\theta,2} \\ \vdots \\ X_t^{\theta,N} \end{bmatrix} + \theta_t \begin{bmatrix} u^1 \\ u^2 \\ \vdots \\ u^N \end{bmatrix} \\ &=: A\mathbf{X}_t^\theta + \theta_t \mathbf{u}, \end{aligned}$$

Optimal Control with Finite Banks II

- The volatility matrix is given by

$$\Sigma := \begin{bmatrix} \sigma_0 & \sigma_1 & 0 & \cdots & 0 \\ \sigma_0 & 0 & \sigma_2 & \cdots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ \sigma_0 & 0 & 0 & \cdots & \sigma_N \end{bmatrix}_{N \times (N+1)}.$$

- Define the parameterized Hamiltonian:

$$\mathcal{H}(t, \mathbf{x}, \mathbf{p}, M; \mathbf{y}) := \inf_{\theta \in \Theta} \left\{ \mathbf{b}(\mathbf{x}, \theta)^\top \mathbf{p} + \frac{1}{2} \text{tr}(\Sigma \Sigma^\top M) + R_N(\mathbf{x}, \mathbf{y}; \theta) \right\}.$$

Optimal Control with Finite Banks III

- Consider the following parameterized HJB equation:

$$\begin{cases} -\frac{\partial V}{\partial t}(t, \mathbf{x}; \mathbf{y}) - \mathcal{H}(t, \mathbf{x}, \nabla_{\mathbf{x}} V(t, \mathbf{x}; \mathbf{y}), \nabla_{\mathbf{x}}^2 V(t, \mathbf{x}; \mathbf{y}); \mathbf{y}) = 0, \\ V(T, \mathbf{x}; \mathbf{y}) = L_N(\mathbf{x}, \mathbf{y}), \end{cases}$$

- The HJB equation admits a unique classical solution (**Theorem IV.6.2** of [Fleming and Rishel \(1975\)](#)).

Optimal Control with Finite Banks IV

- Optimal control:

$$\theta_t^{*,N} = f^*(t, \mathbf{X}_t^*; \mathbf{Y}) = \Pi_{\Theta} \left(-\frac{1}{2\lambda} \sum_{j=1}^N u_j \frac{\partial V(t, \mathbf{X}_t^*; \mathbf{Y})}{\partial x_j} \right),$$

where

$$\mathbf{X}_t^* = \mathbf{X}_0 + \int_0^t \mathbf{b}(\mathbf{X}_s^*, f^*(s, \mathbf{X}_s^*; \mathbf{Y})) ds + \Sigma \mathbf{W}_t, \quad t \in [0, T].$$

Our Goals

- 1 The convergence of optimal controls $\theta^{*,N}$ as $N \rightarrow \infty$;
- 2 The limit of $\theta^{*,N}$ as $N \rightarrow \infty$ is the minimizer of a so-called limiting control problem.

Challenges:

- 1 $\theta^{*,N}$ heavily depends on the dimension N which is coming from \mathbf{x} , \mathbf{y} and V .
- 2 Build the rigorous connection between the problem with N banks and the mean field control problem.

Control Problem under Weak Formulation I

- **Canonical space** representation:

$$\Omega_\infty := \Xi^{\mathbb{N}} \times \mathcal{C}_T \times \mathcal{C}_T^{\mathbb{N}} \times \mathcal{L}_T^2, \quad \mathcal{F}_\infty := \mathcal{B}(\Omega_\infty),$$

where $\Xi := \mathbb{R}^2$.

- **coordinate process** $\hat{\mathcal{X}} := (\hat{\zeta}, (\hat{W}^0, \hat{\mathbf{W}}), \hat{\theta})$, i.e., $\hat{\mathcal{X}}(\omega) = \omega$ for all $\omega \in \Omega_\infty$. Here, $\hat{\zeta} := (\hat{\zeta}^1, \hat{\zeta}^2, \dots)^\top$ and $\hat{\mathbf{W}} := (\hat{W}^1, \hat{W}^2, \dots)^\top$.
- **Complete natural filtration** $\hat{\mathbb{F}} = (\mathcal{F}_t^{\hat{\mathcal{X}}})_{t \in [0, T]}$ generated by the coordinate process $\hat{\mathcal{X}}$.

Control Problem under Weak Formulation II

- The space Ω_∞ is equipped with the metric: for $(\gamma, w, \varsigma, \rho)$ and $(\hat{\gamma}, \hat{w}, \hat{\varsigma}, \hat{\rho}) \in \Omega_\infty$,

$$d((\gamma, \varsigma, w, \kappa), (\hat{\gamma}, \hat{\varsigma}, \hat{w}, \hat{\kappa})) := d_1(\gamma, \hat{\gamma}) + d_2(\varsigma, \hat{\varsigma}) + d_3(w, \hat{w}) + d_4(\kappa, \hat{\kappa}),$$

- The metrics d_i for $i = 1, 2, 3, 4$ are given as follows:

$$d_1(\gamma, \hat{\gamma}) := \sum_{i=1}^{\infty} 2^{-i} \frac{|\gamma_i - \hat{\gamma}_i|}{1 + |\gamma_i - \hat{\gamma}_i|}, \quad \gamma = (\gamma_i)_{i=1}^{\infty}, \quad \hat{\gamma} = (\hat{\gamma}_i)_{i=1}^{\infty} \in \Xi^{\mathbb{N}};$$

$$d_2(\varsigma, \hat{\varsigma}) := \|\varsigma - \hat{\varsigma}\|_T = \sup_{t \in [0, T]} |\varsigma_t - \hat{\varsigma}_t|, \quad \varsigma, \hat{\varsigma} \in \mathcal{C}_T;$$

$$d_3(w, \hat{w}) := \sum_{i=1}^{\infty} 2^{-i} \frac{\|w_i - \hat{w}_i\|_T}{1 + \|w_i - \hat{w}_i\|_T}, \quad w = (w_i)_{i=1}^{\infty}, \quad \hat{w} = (\hat{w}_i)_{i=1}^{\infty} \in \mathcal{C}_T^{\mathbb{N}};$$

$$d_4(\kappa, \hat{\kappa}) := \|\kappa - \hat{\kappa}\|_{\mathcal{L}_T^2} = \left(\int_0^T |\kappa_t - \hat{\kappa}_t|^2 dt \right)^{\frac{1}{2}}, \quad \kappa, \hat{\kappa} \in \mathcal{L}_T^2.$$

Control Problem under Weak Formulation III

Definition 1 (Weak Controls)

Given the law $\nu \in \mathcal{P}(\Xi^{\mathbb{N}})$, let $\mathcal{Q}(\nu)$ be the set of probability measures Q on $(\Omega_{\infty}, \mathcal{F}_{\infty})$ satisfying

- (i) $Q \circ \hat{\zeta}^{-1} = \nu$;
- (ii) $(\widehat{W}^0, \widehat{W})$ is a sequence of independent Wiener processes on $(\Omega_{\infty}, \widehat{\mathcal{F}}_{\infty}, \widehat{\mathbb{F}}, Q)$;
- (iii) $\widehat{\theta} \in \mathbb{U}^{\mathcal{Q}, \widehat{\mathbb{F}}}$.

- Control problem **under weak formulation** (for fixed N):

$$V_N^R(\nu) = \inf_{Q \in \mathcal{Q}(\nu)} J_N^R(Q);$$

$$J_N^R(Q) := \mathbb{E}^Q \left[L_N(\widehat{\mathbf{X}}_T^{\widehat{\theta}, N}, \widehat{\mathbf{Y}}^N) + \int_0^T R_N(\widehat{\mathbf{X}}_t^{\widehat{\theta}, N}, \widehat{\mathbf{Y}}^N; \widehat{\theta}_t) dt \right].$$

Main Steps:

- 1 Identification of explicit limiting optimization problem with infinitely many banks (i.e., $N \rightarrow \infty$).
- 2 Equivalence of the value functions under strong and weak formulations.
- 3 The minimizer of finite-dimensional optimization problem tends to the minimizer of explicit limiting optimization problem (i.e., **Gamma-convergence**).
- 4 The minimizer of the limiting optimization problem is an approximate optimal weak control to the strong control problem.

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Convergence of Empirical process I

- Let $Q_N \in \mathcal{Q}(\nu)$ and $\hat{\mathcal{X}}^N$ be the corresponding coordinate process to Q_N . $\hat{\mathbf{X}}^N := (\hat{X}_t^{N,1}, \dots, \hat{X}_t^{N,N})_{t \in [0, T]}^\top$ solves the following system:

$$d\hat{X}_t^{N,i} = \frac{a_i}{N} \sum_{j=1}^N (\hat{X}_t^{N,j} - \hat{X}_t^{N,i}) dt + u_i \theta_t^N dt + \sigma_i d\hat{W}_t^{N,i} + \sigma_0 d\hat{W}_t^{N,0}.$$

- The **empirical measure-valued process** $\mu^N = (\mu_t^N)_{t \in [0, T]}$ under $Q_N \in \mathcal{Q}(\nu)$ is defined by

$$\mu_t^N := \frac{1}{N} \sum_{i=1}^N \delta_{(\xi_i, \hat{Y}_t^{N,i}, \hat{X}_t^{N,i})} \in \mathcal{P}_2(E), \quad t \in [0, T].$$

Convergence of Empirical process II

- **Assumption (\mathbf{A}_{s2}):** For any $\gamma = (x^i, y^i)_{i \geq 1} \in \Xi^{\mathbb{N}}$, define $I_N : \gamma \mapsto \frac{1}{N} \sum_{i=1}^N \delta_{(\xi_i, y^i, x^i)} \in \mathcal{P}_2(E)$ for $N \geq 1$, there exists a measurable mapping $I_* : \Xi^{\mathbb{N}} \rightarrow \mathcal{P}_2(E)$ such that

$$\nu \left(\left\{ \gamma \in \Xi^{\mathbb{N}} : \lim_{N \rightarrow \infty} \mathcal{W}_{E,2}(I_N(\gamma), I_*(\gamma)) = 0 \right\} \right) = 1.$$

- Let \mathbb{Q}^N be the law of empirical distribution:

$$\mathbb{Q}^N = \mathcal{Q}_N \circ (\mu_0^N, \hat{\theta}^N, \mu^N)^{-1}.$$

Convergence of Empirical process III

Theorem 2

Let (\mathbf{A}_{s1}) holds. We assume in addition that

$$Q_N \circ (\mu_0^N, \hat{\theta}^N)^{-1} \Rightarrow \nu_0,$$

as $N \rightarrow \infty$, for some $\nu_0 \in \mathcal{P}(\mathcal{P}_2(E) \times \mathcal{L}^2)$. Then, it holds that

- $(\mathbb{Q}^N)_{N=1}^\infty$ is relatively compact in $\mathcal{P}_2(\hat{S})$.

where $\hat{S} := \mathcal{P}_2(E) \times \mathcal{L}_T^2 \times S$ and $S := C([0, T]; \mathcal{P}_2(E))$

Convergence of Empirical process IV

• Sketch of Proof

- 1 Introduce the metric on \hat{S} as: for $(\nu, \theta, \rho), (\hat{\nu}, \hat{\theta}, \hat{\rho}) \in \hat{S}$,

$$d_{\hat{S}}((\nu, \theta, \rho), (\hat{\nu}, \hat{\theta}, \hat{\rho})) := \mathcal{W}_{E,2}(\nu, \hat{\nu}) + \|\theta - \hat{\theta}\|_{\mathcal{L}_T^2} + d_S(\rho, \hat{\rho}),$$

where $d_S(\rho, \hat{\rho}) := \sup_{t \in [0, T]} \mathcal{W}_{E,2}(\rho_t, \hat{\rho}_t)$, for $\rho, \hat{\rho} \in S$.

- 2 By [Villani \(2003\)](#), $(\mathbb{Q}^N)_{N=1}^\infty$ is relatively compact in $\mathcal{P}_2(\hat{S})$ if and only if

- (i) $(\mathbb{Q}^N)_{N=1}^\infty$ is **tight** (relatively compact) in $\mathcal{P}(\hat{S})$;
- (ii) $\lim_{R \rightarrow \infty} \sup_{N \geq 1} \int_{\{\mu \in \hat{S}; d_S^2(\mu, \hat{\mu}) \geq R\}} d_S^2(\mu, \hat{\mu}) \mathbb{Q}^N(d\mu) = 0$.

Convergence of Empirical process V

- **Characterize the limiting process:** if the law of an \hat{S} -valued r.v. $(\tilde{\mu}_0, \tilde{\theta}, \tilde{\mu})$ defined on some probability space $(\tilde{\Omega}, \tilde{\mathcal{F}}, \tilde{\mathbb{P}})$ is the limiting point, then $\tilde{\mu} = (\tilde{\mu}_t)_{t \in [0, T]}$ satisfies the **stochastic FPK** equation that

$$\langle \tilde{\mu}_t, \phi \rangle = \langle \tilde{\mu}_0, \phi \rangle + \int_0^t \langle \tilde{\mu}_s, \mathcal{A}^{\tilde{\mu}_s, \tilde{\theta}_s} \phi \rangle ds + \sigma_0 \int_0^t \langle \tilde{\mu}_s, \phi' \rangle d\tilde{W}_s^0, \quad \forall \phi \in C_b^2(\mathbb{R}),$$

where

$$\mathcal{A}^{m, \theta} \phi(x) := g^{m, \theta}(x) \phi'(x) + \frac{\sigma^2 + \sigma_0^2}{2} \phi''(x), \quad m \in \mathcal{P}_2(E), \theta \in \Theta,$$

and $g^{m, \theta}(x) = a \left(\int_E z m(d\xi, dy, dz) - x \right) + u\theta$.

Convergence of Empirical process VI

Proposition 3

If $\tilde{\mu}_0$ has a square-integrable density w.r.t. Lebesgue measure, then the stochastic FPK equation admits a unique solution. Thus, $\{\mathbb{Q}^N\}_{N \geq 1}$ converges in $\mathcal{P}_2(\hat{S})$.

- **Sketch of Proof**

- Well-posedness of the following **linear** SDE: for any **fixed** $\nu \in \mathcal{S}$, $\forall \phi \in C_b^2(\mathbb{R})$,

$$\langle \vartheta_t, \phi \rangle = \langle \tilde{\mu}_0, \phi \rangle + \int_0^t \langle \vartheta_s, \mathcal{A}^{\nu_s, \tilde{\theta}_s} \phi \rangle ds + \sigma_0 \int_0^t \langle \vartheta_s, \phi' \rangle d\tilde{W}_s^0. \quad (4.1)$$

Convergence of Empirical process VII

- 1 Change the $\mathcal{P}(E)$ -valued process to an L^2 -valued process:

$$T_\delta \vartheta_t(x) := \int_{\mathbb{R}^5} G_\delta(x - z) \vartheta_t(da, du, d\sigma, dy, dz),$$

where $G_\delta(x) = \frac{1}{\sqrt{2\pi\delta}} e^{-\frac{x^2}{2\delta}}$ is the **heat kernel**.

- 2 If $\tilde{\mu}_0$ has an L^2 -density with respect to Lebesgue measure., then so does ϑ_t , for any $t \in [0, T]$.

Convergence of Empirical process VIII

- ③ If ϑ^1 and ϑ^2 are two $\mathcal{P}(E)$ -valued solutions of (4.1), then $\vartheta_t := \vartheta_t^1 - \vartheta_t^2$ satisfies

$$\tilde{\mathbb{E}} [\|T_\delta \vartheta_t\|_{L^2}^2] \leq C \int_0^t \tilde{\mathbb{E}} [\|T_\delta(|\vartheta_s|)\|_{L^2}^2] ds,$$

where the constant $C > 0$ is independent of ϑ^1 and ϑ^2 .

- ④ Denote $\|\vartheta\|_{L^2}$ the L^2 -norm of the density function of the signed measure ϑ .

Convergence of Empirical process IX

- 5 For a complete orthonormal basis $(\psi_j)_{j \geq 1}$, it holds that

$$\begin{aligned}
 \tilde{\mathbb{E}} \left[\|\vartheta_t\|_{L^2}^2 \right] &= \tilde{\mathbb{E}} \left[\sum_j \langle \psi_j, \vartheta_t \rangle^2 \right] = \tilde{\mathbb{E}} \left[\sum_j \lim_{\delta \rightarrow 0} \langle T_\delta \psi_j, \vartheta_t \rangle^2 \right] \\
 &= \tilde{\mathbb{E}} \left[\sum_j \lim_{\delta \rightarrow 0} \langle T_\delta \vartheta_t, \psi_j \rangle_{L^2}^2 \right] \leq \lim_{\delta \rightarrow 0} C \int_0^t \tilde{\mathbb{E}} \left[\|T_\delta(|\vartheta_s|)\|_{L^2}^2 \right] ds \\
 &\leq C \int_0^t \tilde{\mathbb{E}} \left[\|\vartheta_s\|_{L^2}^2 \right] ds = C \int_0^t \tilde{\mathbb{E}} \left[\|\vartheta_s\|_{L^2}^2 \right] ds.
 \end{aligned}$$

- 6 By Gronwall's inequality, the linear SDE (4.1) has a unique solution.

Convergence of Empirical process X

- Well-posedness of the following **conditional McKean-Vlasov equation**:

$$\begin{cases} dX_t = \tilde{a} \left(X_t - \int_E x \nu_t(d\xi, dy, dx) \right) dt + \tilde{u} \tilde{\theta}_t dt + \tilde{\sigma} d\tilde{W}_t + \sigma_0 d\tilde{W}_t^0, \\ \nu_t = \mathcal{L}((\tilde{a}, \tilde{u}, \tilde{\sigma}, \tilde{Y}, X_t) | \tilde{\mathcal{G}}_t), \end{cases}$$

where $\tilde{\zeta} = (\tilde{a}, \tilde{u}, \tilde{\sigma}, \tilde{Y}, X_0)$ is an E -valued r.v. with $\tilde{\mathbb{P}} \circ \tilde{\zeta}^{-1} = \tilde{\mu}_0$ and $\tilde{\mathcal{G}}_t := \sigma(\tilde{\zeta}) \vee \sigma(\tilde{W}_s^0, \tilde{\theta}_s; s \leq t)$.

- For any $r > 0$, define Banach space

$$\mathbb{H}_r := \left\{ X : \tilde{\mathbb{F}}\text{-adapted process, } \|X\|_r := \tilde{\mathbb{E}} \left[\int_0^T e^{-rt} |X_t| dt \right] < \infty \right\}.$$

Convergence of Empirical process XI

- 2 For any $X^{(i)} \in \mathbb{H}_r$ and $\nu_t^{(i)} = \mathcal{L}((\tilde{a}, \tilde{u}, \tilde{\sigma}, \tilde{Y}, X_t^{(i)}) | \tilde{\mathcal{G}}_t)$, $i = 1, 2$, define

$$\mathcal{Z}_t(X^{(i)}) := X_0 + \tilde{a} \int_0^t \left(\int_E x \nu_s^{(i)}(d\xi, dy, dx) - X_s^{(i)} \right) ds + \tilde{u} \int_0^t \tilde{\theta}_s ds + \tilde{\sigma} \tilde{W}_t + \sigma_0 \tilde{W}_t^0.$$

- 3 For any $r > 0$,

$$\left\| \mathcal{Z}(X^{(1)}) - \mathcal{Z}(X^{(2)}) \right\|_r \leq \frac{2K}{r} \left\| X^{(1)} - X^{(2)} \right\|_r.$$

- 4 Then the result follows from the contraction mapping theorem.

Convergence of Empirical process XII

- Well-posedness of the **stochastic FPK equation**.

- Let $\nu^{(1)}, \nu^{(2)}$ be two solutions. Consider the following SDE:

$$dX_t^{(1)} = \tilde{a} \left(X_t^{(1)} - \int_E x \nu_t^{(1)}(d\xi, dy, dx) \right) dt + \tilde{u} \tilde{\theta}_t dt + \tilde{\sigma} d\tilde{W}_t + \sigma_0 d\tilde{W}_t^0.$$

- Then $\vartheta_t^{(1)} = \mathcal{L}((\tilde{a}, \tilde{u}, \tilde{\sigma}, \tilde{Y}, X_t^{(1)}) | \tilde{\mathcal{G}}_t)$ is a solution to the linear equation (by Itô's formula) [$\nu^{(1)}$ solves FPK]

$$\langle \vartheta_t^{(1)}, \phi \rangle = \langle \tilde{\mu}_0, \phi \rangle + \int_0^t \langle \vartheta_s^{(1)}, \mathcal{A}^{\nu_s^{(1)}, \tilde{\theta}_s} \phi \rangle ds + \sigma_0 \int_0^t \langle \vartheta_s^{(1)}, \phi' \rangle d\tilde{W}_s^0.$$

- Thus $\nu^{(1)} = \vartheta^{(1)}$, and then $(X^{(1)}, \nu^{(1)})$ is a solution to the **conditional McKean-Vlasov equation**.

Convergence of Empirical process XIII

- 4 Similarly, $(X^{(2)}, \nu^{(2)})$ also is a solution to the conditional McKean-Vlasov equation.
- 5 By the uniqueness of solution to the conditional McKean-Vlasov equation, we have $\nu^{(1)} = \nu^{(2)}$.

Convergence of Objective Functionals

Theorem 4

Let (\mathbf{A}_{s1}) and (\mathbf{A}_{s2}) hold. Then, $\lim_{N \rightarrow \infty} J_N^R(Q) = J^R(Q)$. Here,

$$J^R(Q) := \alpha \int_S \langle \rho_T, L \rangle \widehat{Q}_\mu(d\rho) + \beta \int_0^T \left(\int_S \langle \rho_t, L \rangle \widehat{Q}_\mu(d\rho) \right) dt \\ + \lambda \mathbb{E}^Q \left[\int_0^T |\widehat{\theta}_t|^2 dt \right],$$

where \widehat{Q}_μ is the weak limit of

$$\widehat{Q}_\mu^N := Q_N \circ (\widehat{\mu}^N)^{-1}.$$

• Sketch of Proof

- ① By Thm 7.12 in [Villani \(2003\)](#),

$$h_N(t) := \int_S \langle \rho_t, L \rangle \widehat{\mathbb{Q}}_\mu^N(d\rho) \rightarrow \int_S \langle \rho_t, L \rangle \widehat{\mathbb{Q}}_\mu(d\rho), \quad \forall t \in [0, T], \quad N \rightarrow \infty.$$

- ② By the [uniform integrability](#) of $\{h_N(t)\}_{N \geq 1}$, we have

$$\lim_{N \rightarrow \infty} \int_0^T h_N(t) dt = \int_0^T \left(\int_S \langle \rho_t, L \rangle \widehat{\mathbb{Q}}_\mu(d\rho) \right) dt.$$

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Gamma-Convergence I

- Metrize $\mathcal{Q}(\nu)$ by taking 2nd-order Wasserstein distance \mathcal{W}_2 .
- Γ -convergence of $(J_N^R(Q))_{N=1}^\infty$ on metric space $(\mathcal{Q}(\nu), \mathcal{W}_2)$ is defined as (see, e.g. Braides (2014)):

Definition 5 (Gamma-Convergence)

We call $J_N^R : \mathcal{Q}(\nu) \rightarrow \mathbb{R}$ Γ -converges to $J^R : \mathcal{Q}(\nu) \rightarrow \mathbb{R}$, i.e.,

small $J^R = \Gamma\text{-}\lim_{N \rightarrow \infty} J_N^R$ on $\mathcal{Q}(\nu)$, if the following conditions hold:

- (lim inf inequality): For any $Q \in \mathcal{Q}(\nu)$ and every sequence $(Q_N)_{N=1}^\infty$ converging to Q in $(\mathcal{Q}(\nu), \mathcal{W}_2)$, we have that $\liminf_{N \rightarrow \infty} J_N^R(Q_N) \geq J^R(Q)$;
- (lim sup inequality): For any $Q \in \mathcal{Q}(\nu)$, there exists a sequence $(\hat{Q}_N)_{N=1}^\infty$ which converges to Q in $(\mathcal{Q}(\nu), \mathcal{W}_2)$ (this sequence is said to be a Γ -realising sequence), we have that $\limsup_{N \rightarrow \infty} J_N^R(\hat{Q}_N) \leq J^R(Q)$.

Gamma-Convergence II

- The following proposition implies both the \liminf and \limsup inequalities.

Proposition 6

Let assumptions (\mathbf{A}_{s1}) , (\mathbf{A}_{s2}) and (\mathbf{A}_Θ) hold. For any $\{Q_N\}_{N \geq 1}$, $Q \subset \mathcal{Q}(\nu)$ satisfying $\lim_{N \rightarrow \infty} \mathcal{W}_{\Omega_\infty, 2}(Q_N, Q) = 0$, let $(\hat{\zeta}^N, (\hat{W}^{N,0}, \hat{W}^N), \hat{\theta}^N)$ (resp. $(\hat{\zeta}, (\hat{W}^0, \hat{W}), \hat{\theta})$) be the corresponding coordinate process to Q_N (resp. Q). If $I_(\hat{\zeta})$ has a square-integrable density (under Q) w.r.t. Lebesgue measure, then we have*

$$\lim_{N \rightarrow \infty} J_N^R(Q_N) = J^R(Q).$$

Precompactness of the Minimizer I

Construct a precompact sequence of minimizers:

- The equivalence of the value functions under strong and weak formulations. That is,

$$\inf_{\theta \in \mathbb{U}^{\mathbb{P}, \mathbb{F}}} J_N(\theta) = \inf_{Q \in \mathcal{Q}(\nu)} J_N^R(Q).$$

- Continuity of the objective functional. $J_N(\theta) : \mathbb{U}^{\mathbb{P}, \mathbb{F}} \rightarrow \mathbb{R}$ is continuous with respect to the metric induced by the \mathbb{H}^2 -norm.
- By **Ekeland's variational principle**: there exists a minimizing sequence $\{\theta^k\}_{k \geq 1} \subset \mathbb{U}^{\mathbb{P}, \mathbb{F}}$, s.t.

$$J_N(\theta^k) \leq J_N(\theta) + \frac{1}{k} \|\theta^k - \theta\|_{\mathbb{H}^2}, \quad \forall \theta \in \mathbb{U}^{\mathbb{P}, \mathbb{F}}.$$

Precompactness of the Minimizer II

- **Characterize the minimizing sequence.** There exists $\chi^k \in \mathbb{H}^2$ with $\|\chi^k\|_{\mathbb{H}^2} \leq 1$, such that

$$\theta_t^k = \Pi_{\Theta} \left(-\frac{1}{2\lambda} \sum_{i=1}^N u_i p_t^{k,i} - \frac{1}{2\lambda k} \chi_t^k \right).$$

Here $(\mathbf{p}^k, \mathbf{q}^k)$ is the unique solution to the adjoint equation

$$d\mathbf{p}_t^k = - \left[A^\top \mathbf{p}_t^k + \frac{2\beta}{N} (\mathbf{X}_t^k - \mathbf{Y}) \right] dt + \mathbf{q}_t^k d\mathbf{W}_t, \quad t \in [0, T),$$

$$\mathbf{p}_T^k = \nabla_{\mathbf{x}} L_N(\mathbf{X}_T^k, \mathbf{Y}) = \frac{2\alpha}{N} (\mathbf{X}_T^k - \mathbf{Y}),$$

where $X^k = (X_t^k)_{t \in [0, T]}$ satisfies $d\mathbf{X}_t^k = \mathbf{b}(\mathbf{X}_t^k, \theta_t^k) dt + \Sigma d\mathbf{W}_t^0$.

Precompactness of the Minimizer III

- Construct admissible relaxed control sequence: $Q^k := \mathbb{P}_\circ(\zeta, (W^0, \mathbf{W}), \theta^k)^{-1}$ and show the tightness of $(Q^k)_{k \geq 1}$. Thus, Q^k converge to some $Q^{N,*}$ weakly (along a subsequence).
- Using [Skorokhod's representation theorem](#), we have:

$$J_N^R(Q^{N,*}) = \lim_{k \rightarrow \infty} J_N(\theta^k) = \inf_{\theta \in \mathbb{U}^{\mathbb{P}, \mathbb{F}}} J_N(\theta) = \inf_{Q \in \mathcal{Q}(\nu)} J_N^R(Q).$$

- The sequence of minimizers $(Q^{N,*})_{N \geq 1}$ is tight.

Main Results

- The main implication of (i) Γ -convergence and (ii) the precompactness of the sequence of minimizers:

Theorem 7

Let (\mathbf{A}_{s1}) and (\mathbf{A}_{s2}) hold. Then, as $N \rightarrow \infty$,

$$\inf_{Q \in \mathcal{Q}(\nu)} J_N^R(Q) \rightarrow \min_{Q \in \mathcal{Q}(\nu)} J^R(Q),$$

where *the minimum of $J^R(Q)$ exists*. Moreover, if the minimizer $(Q^{N,*})_{N=1}^{\infty} \subset \mathcal{Q}(\nu)$ (up to a subsequence) converges to some $Q^* \in \mathcal{Q}(\nu)$ (the existence of Q^* has been guaranteed), then Q^* *minimizes $J^R(Q)$* .

Approximate Optimal Weak Control

Corollary 8

Let $Q^* \in \mathcal{Q}(\nu)$ be the **minimizer** of $J^R(Q)$. Then

$$\lim_{N \rightarrow \infty} \left| J_N^R(Q^*) - \inf_{\theta \in \mathbb{U}^{\mathbb{P}, \mathbb{F}}} J_N(\theta) \right| = 0.$$

- In fact, we have that, as $N \rightarrow \infty$,

$$\begin{aligned} \left| J_N^R(Q^*) - \inf_{\theta \in \mathbb{U}^{\mathbb{P}, \mathbb{F}}} J_N(\theta) \right| &= \left| J_N^R(Q^*) - \inf_{Q \in \mathcal{Q}(\nu)} J_N^R(Q) \right| \\ &\leq |J_N^R(Q^*) - J^R(Q^*)| + \left| \inf_{Q \in \mathcal{Q}(\nu)} J^R(Q) - \inf_{Q \in \mathcal{Q}(\nu)} J_N^R(Q) \right| \rightarrow 0. \end{aligned}$$

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Thank you!